

SOLUTIONS

① One-dimensional wave equation for the string,  $0 \leq x \leq l$ :

$$\frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = 0 \quad (1)$$

with boundary conditions  $u(0,t) = 0$   
 $u_x(l,t) = 0$

[ fixed end at  $x=0$ ; "free" end at  $x=l$  ]

Seek solution in the form:

$$u(x,t) = v(x)q(t) \quad (2)$$

Substituting into (1):

$$v(x) \frac{\partial^2 q}{\partial t^2} - q(t) c^2 \frac{\partial^2 v}{\partial x^2} = 0,$$

dividing by  $v(x)q(t)$  and replacing partial derivatives by total ( $\partial \rightarrow d$ ):

$$\frac{1}{q(t)} \frac{d^2 q}{dt^2} - \frac{c^2}{v(x)} \frac{d^2 v}{dx^2} = 0 \quad (3)$$

function of  $t$  only                      function of  $x$  only

The two terms in (3) must be constants, i.e., denoting the constant  $-\omega^2$ :

$$\frac{1}{q(t)} \frac{d^2 q}{dt^2} = -\omega^2 \quad (4)$$

[ We will see below that the separation constant must be negative. ] Eq. (4) gives:  $q'' + \omega^2 q = 0$ ,

So, the general solution of (4) is

$$q(t) = C_1 \cos \omega t + C_2 \sin \omega t,$$

which can also be written as

$$q(t) = A \cos(\omega t + \phi), \text{ where } \phi \text{ is the initial phase.}$$

Turning to the coordinate part of Eq. (3) now:

$$\frac{c^2}{v(x)} \frac{d^2 v}{dx^2} = -\omega^2$$

$$\frac{d^2 v}{dx^2} = -\frac{\omega^2}{c^2} v(x);$$

Denoting  $\frac{\omega}{c} \equiv k$ , we have:

$$v'' + k^2 v = 0 \quad (5)$$

The general solution of this equation is:

$$v(x) = C_1 \cos kx + C_2 \sin kx.$$

Using the 1st boundary condition,  $u(0, t) = 0$ , we must have  $v(0) = 0$ , hence:  $0 = C_1 \cdot 1 + C_2 \cdot 0$ ,

and  $C_1 = 0$ .

Therefore  $v(x) = C \sin kx$ , where we have renamed  $C_2 \rightarrow C$ .

Using the second boundary condition:  $v'(l) = 0$ :

$$v'(x) = Ck \cos kx$$

$$u_x(l, t) = 0$$

$$Ck \cos kl = 0$$

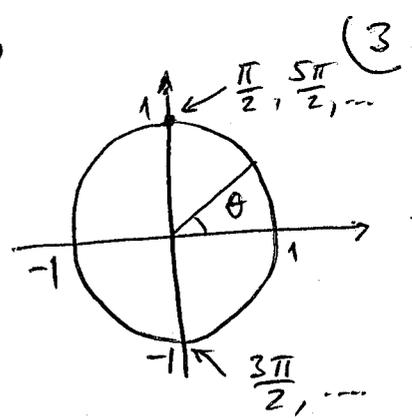
To have a nonzero solution, we require

$$\underline{\cos kl = 0.}$$

For positive  $\theta$ ,  $\cos \theta$  vanishes

$$\text{at } \theta = \frac{\pi}{2}, \frac{3\pi}{2}, \frac{5\pi}{2}, \dots,$$

$$\text{i.e. } \theta = \frac{\pi}{2} + n\pi, \quad n = 0, 1, 2, \dots$$



Hence 
$$kl = \pi \left( n + \frac{1}{2} \right), \quad n = 0, 1, 2, \dots$$

$$k = \frac{\pi}{l} \left( n + \frac{1}{2} \right)$$

$$v_n(x) = C \sin \frac{(n + \frac{1}{2})\pi x}{l} \quad (6)$$

The corresponding frequencies are

$$\omega = kc = \frac{\pi c \left( n + \frac{1}{2} \right)}{l} \equiv \omega_n$$

Combining  $v(x)$ , Eq. (6), with  $q(t)$ , we have:

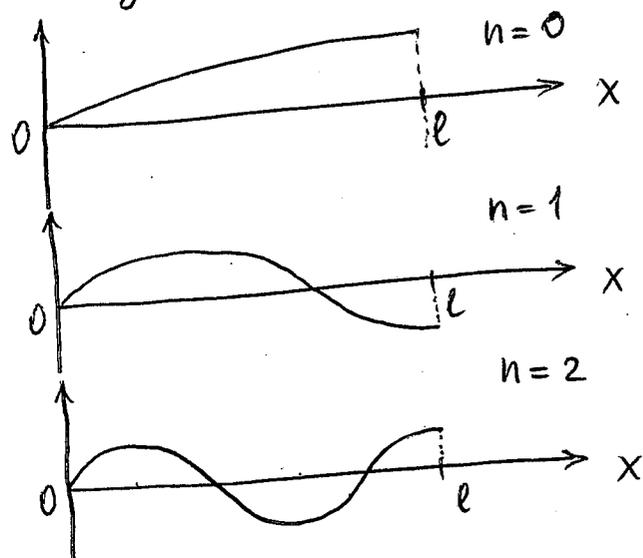
$$u(x, t) = A \sin \frac{(n + \frac{1}{2})\pi x}{l} \cos(\omega_n t + \phi)$$

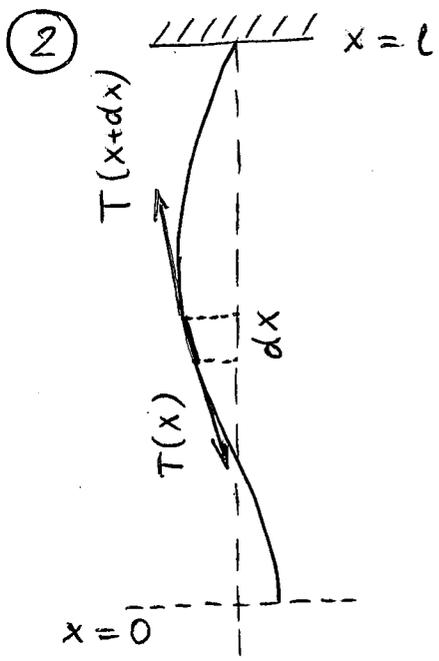
where  $A$  is an arbitrary constant.

These solutions describe harmonic vibrations with frequency  $\omega_n$ . They can be visualised by plotting  $v_n(x)$ .

In these solutions the phase of the sin function increases from 0 at  $x=0$  to  $(n + \frac{1}{2})\pi$

at  $x=l$ . The number of nodes between  $x=0$  and  $x=l$  is  $n$ .





(a) Considering the segment of the rope of length  $dx$  :

its mass is  $\rho dx$ ,

Forces acting on it at the two ends :  $T(x+dx)$  and  $T(x)$ .

Taking their components in the direction perpendicular to  $x$ , we obtain the total force acting on  $dx$  segment in this

direction :

$$T(x+dx) \sin \theta(x+dx) - T(x) \sin \theta(x)$$

$$= \frac{\partial}{\partial x} (T(x) \sin \theta(x)) dx, \quad (1)$$

where  $\theta(x)$  is the angle the rope makes with the  $x$  direction.

If the perpendicular displacement of the rope is  $u(x,t)$ , then, for small displacements and "nearly straight" rope,  $\theta \ll 1$ ,

$$\sin \theta \approx \tan \theta = \frac{\partial u}{\partial x} \quad (2)$$

The acceleration of the segment is  $\frac{\partial^2 u}{\partial t^2}$ , hence by Newton's 2nd law:

$$\rho dx \frac{\partial^2 u}{\partial t^2} = \frac{\partial}{\partial x} (T(x) \frac{\partial u}{\partial x}) dx \quad (3)$$

The tension in the rope at point  $x$  is equal to the weight of the rope below, i.e.  $T = \rho x g$ .

Substituting this into (3) we obtain :

$$\rho \frac{\partial^2 u}{\partial t^2} = \frac{\partial}{\partial x} \left( \rho x g \frac{\partial u}{\partial x} \right) \quad (5)$$

Cancelling  $\rho$  and shifting the term from RHS to LHS we have:

$$\frac{\partial^2 u}{\partial t^2} - g \frac{\partial}{\partial x} \left( x \frac{\partial u}{\partial x} \right) = 0, \quad (4)$$

as required.

(b) Seek solution of (4) in the form:

$$u(x,t) = v(x)q(t). \quad (5)$$

Substituting (5) into (4):

$$v(x) \frac{\partial^2 q}{\partial t^2} - q(t) g \frac{\partial}{\partial x} \left( x \frac{\partial v}{\partial x} \right) = 0$$

Dividing through by  $v(x)q(t)$ :

$$\underbrace{\frac{1}{q(t)} \frac{d^2 q}{dt^2}}_{\text{function of } t} - \underbrace{\frac{g}{v(x)} \frac{d}{dx} \left( x \frac{dv}{dx} \right)}_{\text{function of } x} = 0$$

The two terms must be constants. Choosing the separation constant as  $-\omega^2$ , we have for the temporal part:

$$\frac{1}{q(t)} q'' = -\omega^2$$

$$q'' + \omega^2 q = 0$$

General solution:

$$q(t) = C_1 \cos \omega t + C_2 \sin \omega t$$

$$\text{or } q(t) = A \cos(\omega t + \phi),$$

where  $\phi$  is the initial phase.

Turning to the spatial, coordinate part now: (6)

$$\frac{g}{v(x)} \frac{d}{dx} \left( x \frac{dv}{dx} \right) = -\omega^2$$

$$g \frac{d}{dx} \left( x \frac{dv}{dx} \right) + \omega^2 v(x) = 0 \quad \left. \vphantom{\frac{d}{dx} \left( x \frac{dv}{dx} \right)} \right\} \text{Using product rule}$$

$$g \frac{dv}{dx} + gx \frac{d^2v}{dx^2} + \omega^2 v(x) = 0 \quad : \text{ divide by } g$$

$$x \frac{d^2v}{dx^2} + \frac{dv}{dx} + \frac{\omega^2}{g} v = 0, \quad (6)$$

as required.

(c) New variable  $\xi = \alpha \sqrt{x}$ , i.e.  $x = \xi^2 / \alpha^2$ .

We need to express the derivatives in Eq. (6) in terms of derivatives with respect to  $\xi$ .

$$\frac{dv}{dx} = \frac{dv}{d\xi} \frac{d\xi}{dx} = \frac{dv}{d\xi} \cdot \frac{\alpha}{2\sqrt{x}}$$

$$\frac{d^2v}{dx^2} = \frac{d}{dx} \left( \frac{dv}{dx} \right) = \frac{d}{dx} \left( \frac{dv}{d\xi} \cdot \frac{\alpha}{2\sqrt{x}} \right)$$

$$= \frac{d}{dx} \left( \frac{dv}{d\xi} \right) \cdot \frac{\alpha}{2\sqrt{x}} + \frac{dv}{d\xi} \frac{d}{dx} \left( \frac{\alpha}{2\sqrt{x}} \right)$$

$$= \frac{d^2v}{d\xi^2} \cdot \frac{d\xi}{dx} \cdot \frac{\alpha}{2\sqrt{x}} + \frac{dv}{d\xi} \cdot \left( -\frac{\alpha}{4x^{3/2}} \right)$$

$$= \frac{d^2v}{d\xi^2} \cdot \frac{\alpha^2}{4x} - \frac{\alpha}{4x^{3/2}} \frac{dv}{d\xi}$$

Substituting the derivatives into (6) and expressing  $\sqrt{x}$ ,  $x$ ,  $x^{3/2}$  in terms of  $\xi$ , we have:

$$\frac{\xi^2}{\alpha^2} \left( \frac{d^2v}{d\xi^2} \cdot \frac{\alpha^2}{4\xi^2/\alpha^2} - \frac{\alpha \alpha^3}{4\xi^3} \frac{dv}{d\xi} \right) + \frac{dv}{d\xi} \cdot \frac{\alpha \alpha}{2\xi} + \frac{\omega^2}{g} v = 0$$

$$\frac{\alpha^2}{4} \frac{d^2 v}{d\xi^2} - \frac{\alpha^2}{4\xi} \frac{dv}{d\xi} + \frac{\alpha^2}{2\xi} \frac{dv}{d\xi} + \frac{\omega^2}{g} v = 0 \quad \left. \right\} \times \frac{4}{\alpha^2} \quad (7)$$

$$\frac{d^2 v}{d\xi^2} + \frac{1}{\xi} \frac{dv}{d\xi} + \frac{4\omega^2}{\alpha^2 g} v = 0$$

Choosing  $\frac{4\omega^2}{\alpha^2 g} = 1 \Leftrightarrow \alpha = \frac{2\omega}{\sqrt{g}}$ ,

we have:

$$\frac{d^2 v}{d\xi^2} + \frac{1}{\xi} \frac{dv}{d\xi} + v = 0, \quad (7)$$

as required.

(d) Equation (7) is the Bessel equation for  $m=0$ . Its solution finite at  $x=0$  (bottom end of the rope) ( $\xi=0$ ) is:

$$v = J_0(\xi) = J_0(\alpha\sqrt{x})$$

$$\Rightarrow v = A J_0\left(\frac{2\omega\sqrt{x}}{\sqrt{g}}\right)$$

We can multiply the solution of a homogeneous equation by an arbitrary const.

At the top end,  $x=l$ , the string is fixed, i.e.

$$u(l,t) = 0, \text{ hence, } v(l) = 0:$$

$$J_0\left(\frac{2\omega\sqrt{l}}{\sqrt{g}}\right) = 0$$

Therefore,  $\frac{2\omega\sqrt{l}}{\sqrt{g}} = z_{0,n}$ , where  $z_{0,n}$  is the  $n$ th root of  $J_0(z)$ . So, the frequency is given by

$$\omega = \frac{z_{0,n} \sqrt{g}}{2\sqrt{l}} \equiv \omega_n,$$

$$\text{or } \omega_n = \frac{z_{0,n} \sqrt{g}}{2\sqrt{l}}$$

Substituting this  $\omega$  value into  $v(x)$  we have: (8)

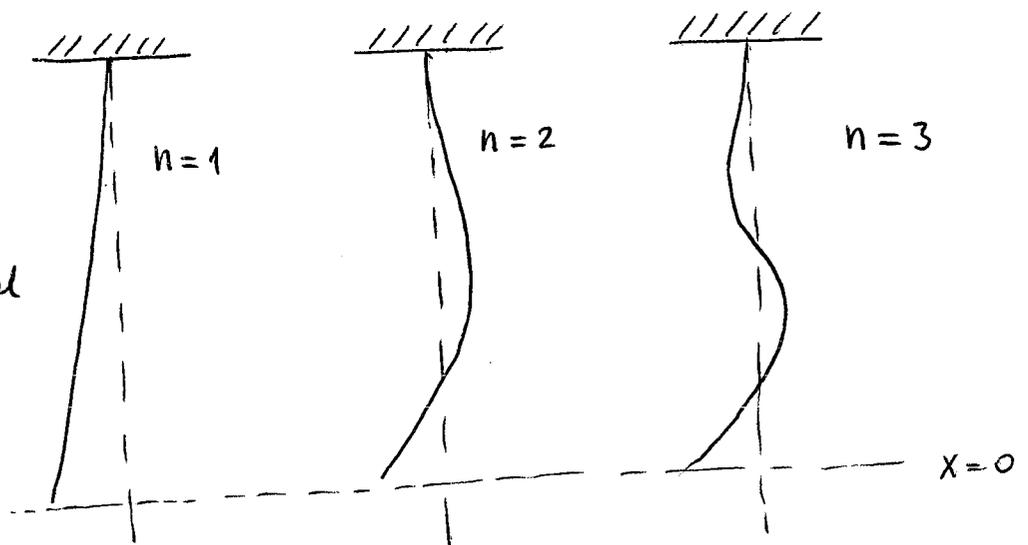
$$v(x) = A J_0 \left( z_{0,n} \sqrt{\frac{x}{l}} \right).$$

(e) Combining the above expression with  $q(t)$  obtained in part (b), we find:

$$u(x,t) = A J_0 \left( z_{0,n} \sqrt{\frac{x}{l}} \right) \cos(\omega_n t + \phi).$$

This solution describes harmonic vibrations of the hanging rope. They can be visualised by sketching the shape of the rope for a fixed  $t$ .

Higher  $n$  obviously correspond to higher vibrational frequencies.



③ (a) 
$$\frac{\partial u}{\partial t} - K \frac{\partial^2 u}{\partial x^2} = 0 \quad (1)$$

For a time independent solution  $u(x,t) = u_s(x)$

$\frac{\partial u_s}{\partial t} = 0$ , hence  $u_s(x)$  satisfies:

$$-K \frac{d^2 u_s}{dx^2} = 0 \quad (2)$$

[Note:  $u_s$  depends on  $x$  only, hence we use the total derivative, not partial.]

The solution of (2), or equivalently,  $u_s'' = 0$  is a linear function:

$$u_s(x) = C_1 x + C_2$$

Using the boundary conditions:  $u_s(0) = T_1$ ,  $u_s(l) = T_2$  (9)

$$C_1 \cdot 0 + C_2 = T_1 \Rightarrow C_2 = T_1$$

$$C_1 l + C_2 = T_2 \Rightarrow C_1 = (T_2 - T_1)/l$$

$$\Rightarrow \underline{u_s(x) = T_1 + \frac{T_2 - T_1}{l} x}, \text{ as required.}$$

(b) Suppose,  $u_0(x, t)$  is a solution of (1) with boundary conditions  $u_0(0, t) = u_0(l, t) = 0$ .

Consider:  $u(x, t) = u_0(x, t) + u_s(x)$ .

Substituting into (1) (left-hand side):

$$\begin{aligned} & \frac{\partial}{\partial t} (u_0(x, t) + u_s(x)) - K \frac{\partial^2}{\partial x^2} (u_0(x, t) + u_s(x)) \\ &= \underbrace{\frac{\partial u_0}{\partial t} - K \frac{\partial^2 u_0}{\partial x^2}}_0 - \underbrace{K \frac{\partial^2 u_s}{\partial x^2}}_0 = 0. \end{aligned}$$

Hence  $u = u_0 + u_s$  is a solution of the heat eq'n.

At the boundaries:  $u(0, t) = u_0(0, t) + u_s(0) = T_1$ ,  
 $u(l, t) = u_0(l, t) + u_s(l) = T_2$ .

(c) We know from Sec. 2.4 that  $u_0(x, t)$  can be constructed as a sum:

$$u_0(x, t) = \sum_{n=1}^{\infty} B_n \sin \frac{n\pi x}{l} e^{-(n^2\pi^2/e^2)Kt}$$

Hence, the solution that satisfies the boundary conditions  $u(0, t) = T_1$ ,  $u(l, t) = T_2$ , as we have seen in part (b), can be obtained as the sum:

$$u(x, t) = \underbrace{T_1 + \frac{T_2 - T_1}{l} x}_{u_s(x)} + \underbrace{\sum_{n=1}^{\infty} B_n \sin \frac{n\pi x}{l} e^{-(n^2\pi^2/e^2)Kt}}_{u_0(x, t)}$$

To satisfy the initial condition  $u(x, 0) = f(x)$ , (10)  
we require:

$$T_1 + \frac{T_2 - T_1}{l} x + \sum_{n=1}^{\infty} B_n \sin \frac{n\pi x}{l} = f(x)$$

Note:  
 $e^{-(n^2\pi^2/l^2)kt}$   
 equals 1  
 for  $t=0$ .

$$\sum_{n=1}^{\infty} B_n \sin \frac{n\pi x}{l} = f(x) - T_1 - \frac{T_2 - T_1}{l} x$$

Multiplying by  $\sin \frac{m\pi x}{l}$  and integrating over  $x$  between 0 and  $l$ , we use the first of the integrals in Examples (Q.2) and see that only one term, with  $n=m$ , gives a nonzero contribution.

Hence:

$$B_m \frac{l}{2} = \int_0^l \left( f(x) - T_1 - \frac{T_2 - T_1}{l} x \right) \sin \frac{m\pi x}{l} dx$$

$$\Rightarrow B_m = \frac{2}{l} \int_0^l \left[ f(x) - T_1 - \frac{T_2 - T_1}{l} x \right] \sin \frac{m\pi x}{l} dx,$$

as required.

[  $B_n$  is given by the same expression with  $\sin \frac{n\pi x}{l}$  under the integral on the right-hand side.]

(4) Two dimensional wave equation in Cartesian coordinates  $x$  and  $y$  is

$$\frac{\partial^2 u}{\partial t^2} - c^2 \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) = 0, \quad (1)$$

for  $u(x, y, t)$ .

Separating the variables, let us seek solution in the form:

$$u(x, y, t) = v(x)w(y)q(t). \quad (2)$$

Substituting into (1), we have:

$$v(x)w(y) \frac{d^2 q}{dt^2} - c^2 w(y) q(t) \frac{d^2 v}{dx^2} - c^2 v(x) q(t) \frac{d^2 w}{dy^2} = 0 \quad (11)$$

Dividing by  $v(x)w(y)q(t)$ , we get:

$$\frac{1}{q} q'' - c^2 \frac{1}{v} v'' - c^2 \frac{1}{w} w'' = 0 \quad (3)$$

$\underbrace{\frac{1}{q} q''}_{\text{depends on } t}$ 
 $\underbrace{- c^2 \frac{1}{v} v''}_{\text{depends on } x}$ 
 $\underbrace{- c^2 \frac{1}{w} w''}_{\text{depends on } y} = 0$

Hence, each of the terms must be a constant.

Let  $\frac{1}{q} q'' = -\omega^2$  (negative separation constant).

$$q'' + \omega^2 q = 0$$

The general solution is

$$q(t) = C_1 \cos \omega t + C_2 \sin \omega t$$

$$\text{or } q(t) = A \cos(\omega t + \phi)$$

With this choice of separation constant, (3)

becomes:

$$-\omega^2 - c^2 \frac{v''}{v} - c^2 \frac{w''}{w} = 0$$

$$\text{or } c^2 \frac{v''}{v} + c^2 \frac{w''}{w} + \omega^2 = 0$$

$$\text{or } \frac{v''}{v} + \frac{w''}{w} + k^2 = 0, \text{ where } k = \frac{\omega}{c}$$

$$\text{Let } \frac{v''}{v} = -k_1^2, \quad \frac{w''}{w} = -k_2^2, \quad \left. \begin{array}{l} \text{We choose} \\ \text{negative} \\ \text{constants here.} \\ \text{see below.} \end{array} \right\}$$

$$\text{so that } -k_1^2 - k_2^2 + k^2 = 0 \quad (4)$$

Equation for  $v(x)$ :

$$v'' + k_1^2 v = 0$$

General solution:  $v(x) = A \cos k_1 x + B \sin k_1 x$

The boundary conditions  $u(0, y, t) = u(a, y, t) = 0$  applied to (2) mean:  $v(0) = v(a) = 0$ . (12)

Hence  $A = 0$  and  $v(x) = B \sin k_1 x$ , and

$$B \sin k_1 a = 0$$

$$\Rightarrow k_1 a = n\pi, \quad n = 1, 2, \dots$$

$$\underline{k_1 = \frac{n\pi}{a}}$$

Similarly, the equation for  $w(y)$  is

$$w'' + k_2 w = 0.$$

Its solution  $w(y) = C \cos k_2 y + D \sin k_2 y$  satisfies the boundary conditions  $u(x, 0, t) = u(x, b, t) = 0$ , i.e.  $w(0) = w(b) = 0$ , only if  $C = 0$ ,

$$w(y) = D \sin k_2 y, \quad \text{and} \quad \sin k_2 b = 0,$$

$$\text{hence} \quad k_2 b = m\pi, \quad m = 1, 2, \dots$$

$$\underline{k_2 = \frac{m\pi}{b}}$$

[Note that if we chose positive separation constants, e.g.  $\frac{v''}{v} = k_1^2$ , i.e.  $v'' - k_1^2 v = 0$ , the solution would be  $v(x) = A e^{k_1 x} + B e^{-k_1 x}$ , and it would not satisfy  $v(0) = v(a) = 0$  for nonzero  $A$  or  $B$ , for any  $k_1$ .]

$$\text{Substituting } k_1 \text{ and } k_2 \text{ into (4): } k^2 = \frac{n^2 \pi^2}{a^2} + \frac{m^2 \pi^2}{b^2},$$

and the frequency of harmonic vibrations is

$$\omega = ck = \pi c \sqrt{\frac{n^2}{a^2} + \frac{m^2}{b^2}} \equiv \omega_{nm}.$$

The corresponding solution is obtained by combining  $q(t)$ ,  $v(x)$  and  $w(y)$  derived above into (2):

$$u(x, y, t) = A \underbrace{\sin \frac{n\pi x}{a}}_{v(x)} \underbrace{\cos \frac{m\pi y}{b}}_{w(y)} \underbrace{\cos(\omega_{nm} t + \phi)}_{q(t)}.$$

arbitrary constant  $\uparrow$